Science Steering Committee Meeting

Staff Astronomer and Adaptive Optics Presentations

Virtual Meeting via Zoom

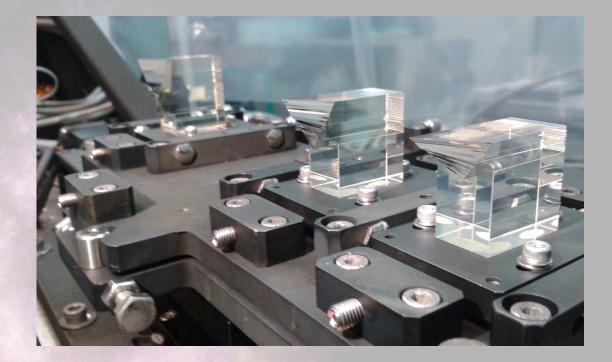
November 11, 2020

Instrument Reports

Group 2 KCWI, DEIMOS, NIRC2, ESI

Keck Cosmic Web Imager

- Bench mounted IFU at K2 Nasmyth
- Range from 3500 to 5600 Angstrom
- Seeing limited
- Resolution from1,000 to 20,000
- FOV 20" x (8, 16, or 33)"
- Efficiency > 20%



KCWI Risk Matrix

	Very Likely >70% within year					
	Probable >35% within year	Minor dewar leak				
Likelihood of Occurrence	Possible >5% within year	Software issues	Mechanisms problems			Extended loss of power causes overcooling of detector
	Unlikely <5% within year				Mechanism failure	Major dewar leak
	Very unlikely <1% within year					Damage to instrument during KCRM installation. Spill during cryo fill.
		Negligible: Little to no impact on Observation	Minor: Observation Compromised	Moderate: Observation Interrupted	Serious: Instrument Down one Night	Major: Instrument Down Indefinitely
				Risk Severity, In	npact	

Activities

Project	Description	Status
Pipeline	Conversion to Python and adoption of Keck DRP Framework	Complete
Startup	Complete automation of the startup procedure	Complete
Autofill	Overhaul and upgrade of autofill system	Complete
Dewar fix	Repair or replacement of leaking dewar	Awaiting KCRM
BH1	Delivery of BH1 grating	Awaiting KCRM
Charge on detector	Fix for excessive charge injected in the detector after a binning switch	Deferred / Addressed in software
Polarimeter	Commissioning of polarimeter	Scheduled for December
Pipeline	Deployment of new pipeline and prototype of DSI end-to-end data flow	Scheduled for December

New KCWI pipeline

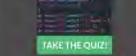


Docs » Keck Cosmic Web Imager DRP's

O Edit on GitHub

Search dors

Installing KCWI_DRP Quick Start Configuration Parameters The startup script The KCWI DRP: basic concepts Primitives/API Updating documentation



Beat Triplebyte's online coding quiz. Get offers from top companies, Skip resumes & recruiters.

Sponsored Ads served endeally

Keck Cosmic Web Imager DRP's

KCWI_DRP is a Python based data reduction pipeline (DRP) developed by the KCWI team at Caltech in collaboration with the W. M. Keck Observatory Scientific Software Group. While the algorithms and the reduction steps are based on the previous IDL pipeline (KDERP), this pipeline uses a new frame-by-frame, event-driven approach, and relies on the Keck DRP Framework (provide link)

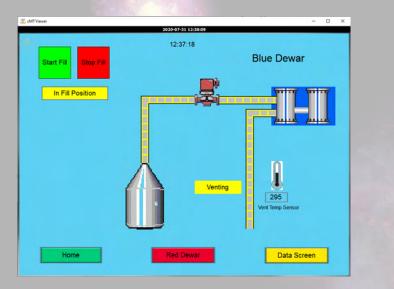
Release 0.1

What this version provides

- · First end-to-end version including all the reduction step of the IDL pipeline
- Three execution modes
 - Reduce all files in a directory in the order in which they appear
 - Reduce all files after grouping them by file type and in the correct order
 - Monitor a directory for new files and reduce them as they appear
- Multi-threading for CPU intensive tasks such as wavelength calibration
- Multi-processing for large datasets

- Event driven
- Reproduces the previous pipeline
- Python: easy to maintain
- Open developed
- Continuous integration
- Same infrastructure as KPF and HISPEC pipelines
- Runs in real time at the telescope and offline for an entire night
- Integral part of DSI
- Currently testing simulated KCRM images

Autofill upgrade



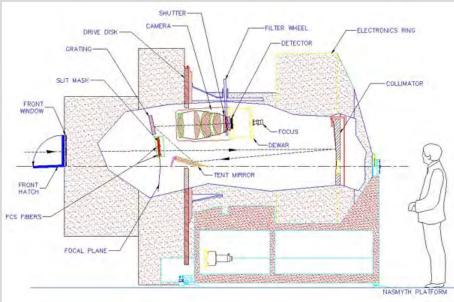




- PLC moved outside of the instrument
- Shared procedure and controls with DEIMOS
- Software and hardware interlocks to prevent spills
- Ready to accommodate KCRM

DEIMOS (DEep Imager and Multi-Object Spectrograph)

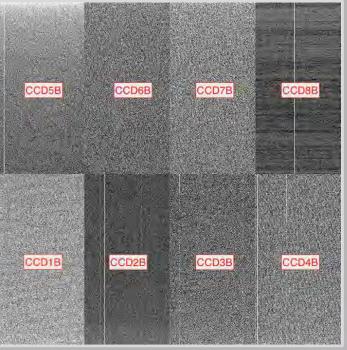




- Institution: UCO/Lick
- PI: Sandy Faber
- First Light: June 3, 2002
- Capabilities: Imaging, MOS and long-slit spectroscopy
- Coverage: 0.4 to 1.0 μm
- Detector: 8x2048x4096 (4x2 mosaic) MIT/LL CCDs (15 μm pix)
- Pixel scale: 0.1185"
- FOV: 16.7'x5'
- Spectral resolution: 1,200 7,600
- Closed-loop flexure compensation system

DEIMOS Risk Matrix

	Very Likely >70% within year				Detector (CCD2, CCD5, CCD8)	
	Probable >35% within year					
Likelihood of Occurrence	Possible >5% within year				Rotator drive	
	Unlikely <5% within year			Optomechanical components	Cryogenics	
	Very unlikely <1% within year					
			Minor: Observation Compromised	Moderate: Observation Interrupted	Serious: Instrument Down one Night	Major: Instrument Down Indefinitely
			F	Risk Severity, Impac	t	



• Detector electronics:

- Serious issues with CCD2, CCD5 and CCD8 in the last year
- Current issues: CCD3A, CCD5A, CCD5B, CCD6A and CCD8A
- Full mosaic is currently operational
- Rotator drive degraded performance:
 - High servo error mitigated by tracking PID.
 - Harmonic drive replaced with a new one on November 2, 2020



November 11, 2020

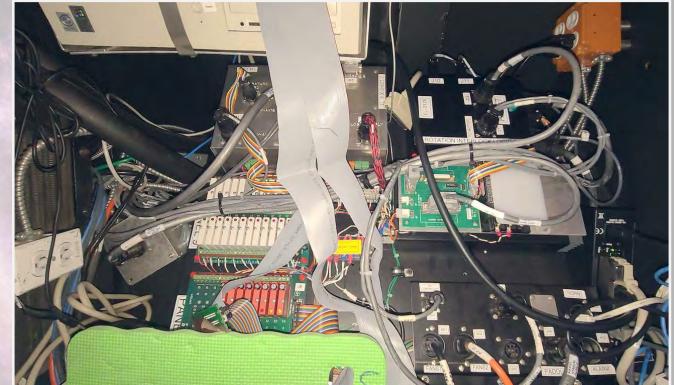
DEIMOS Rotator Control System Upgrade

Motivation:

- To replace Dell Optiplex 110x PC (Red Hat 6.1, 32b.)
- To replace Galil DMC-1840 controller and obsolete kernel driver.

Status: Completed



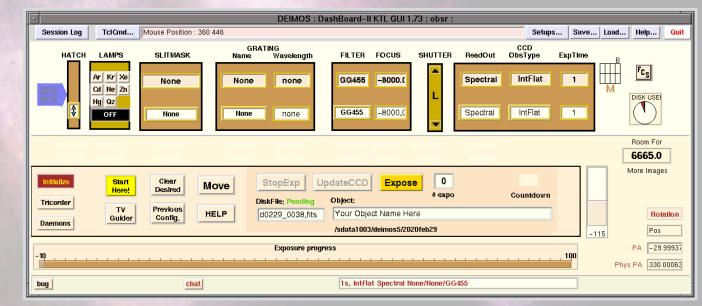


DEIMOS Instrument Host Upgrade

Program information Program ID: ENG000 Observer: Engineering Mechanism control System overview CCD temp (C): -114.9 Rotator angle: -30.0 Rotator angle: -30.0 Rotator angle: -30.0 Grating 3: 12006 Clamps: clamped Clamps: clamped Wavelength: 5597 Filter: C65495 Focus: -8000 Focus: -8000 Shutter: Closed Passive Detector: Idle Details Detector control Details Details Detector control Details Details Object: Test Ready Readout mode: Direct Object: Test Ready Object: IntFlat Object: 1 Progress:		DEIMO	DS instrument c	ontrol	
Program ID: ENG000 Observer: Engineering Mechanism control System overview Mechanism control System overview Hatch: closed Sittmask: None Grating 3: 12006 Clamps: clamped Clamps: clamped VVavelength: 5597 Filter: GG6495 Focus: -8000 Shutter: Closed Details Details Details Details Detector: Idle Details Details Dobject: Test Readout	ile Actions				
Program ID: ENG000 Observer: Engineering Mechanism control Siltmask: None Siltmask: None Grating 3: 12006 Clamps: clamped Clamps: clamped Filter: GG6495 Filter: GG6495 Focus: -8000 Focus: -8000 Shutter: Closed Detector: Idle Detector: Idle Detector: Idle Detector: Idle Details Details Details Details Details Details Details Details Dobject: To Zero Focus: -8000 Closed - Details Details Dobject: To Zero Tost Ready Details Details Direct To Object: Tost Tost Ready Object: SiNGLE:B Object: 1		Proc	aram information	n	
Observer: Engineering Mechanism control System overview Mechanism control CD temp (C): 114.9 Siltimask: None Grating 3: 12006 Clamps: clamped Clamps: clamped Wavelength: 5597 Filter: CG6495 Focus: 8000 Shutter: Closed Detector: Idle Details Details Map mode: SINGLE:B Obs type: IntFlat Integration (s): 1	Program ID: ENG000				
Mechanism controlSystem overviewImage: Hatch:closedImage: CCD temp (C): -114.9Slitmask:NoneNotator angle: -30.0Grating 3:1200GRotator mode: PosClamps:clampedFCS status: PassiveWavelength:5597Init/StowFilter:GG495DetailsFocus:-8000DetailsFocus:-8000DetailsShutter:ClosedDetailsDetector:IdlePassiveReadout mode:DirectReadyObject:TestReadyTo St type:InterflatIntegration (s):1					
Image: Siltmask: None Siltmask: None Grating 3: 1200G Clamps: clamped Clamps: clamped Wavelength: 5597 Filter: GG495 Focus: -8000 Shutter: Closed Detector: Idle Detector: Idle Detector: Idle Cobject: Test Amp mode: SINGLE:B Obs type: InteFlat Integration (s): 1	Observer: Engineer	ing			
Slitmask: None Sitmask: None Grating 3: 12006 Clamps: clamped Wavelength: 5597 To Zero Init/Stow Filter: GG495 Filter: GG495 Focus: -8000 Shutter: Closed Detector: Idle Detector control Details Object: Test Test Integration (s): Integration (s): 1	Mech	anism control		System	overview
Slitmask: None Grating 3: 1200G Clamps: clamped Wavelength: 5597 Filter: GG495 Filter: GG495 Focus: -8000 Focus: -8000 Shutter: Closed Detector: Idle Detector control FCS Readout mode: Direct Amp mode: SINGLE:B Object: Integration (s): 1 1	CO Hatch	closed	*	CCD temp (C):	-114.9
Grating 3: 1200G Clamps: clamped Wavelength: 5597 To Zero Init/Stow Filter: GG495 Focus: -8000 Shutter: Closed Detector: Idle Detector: Idle Detector control Details Details Details Detector: Idle Details Details Dobject: Test Test Test Amp mode: SiNGLE:B Obs type: InitFlat Integration (s): 1				Rotator angle:	-30.0
Clamps: clamped Wavelength: 5597 To Zero Init/Stow Filter: GGG495 Focus: -8000 Focus: -8000 Focus: -8000 Shutter: Closed Detector: Idle Detector: Idle Detector: Idle Detealls Details Detector: Idle Detealls Details Detector: Idle Details Details Object: Tricorde Readout mode: Direct Amp mode: SINGLE:B Obs type: IntFlat Integration (s): 1			-	Rotator mode:	Pos
Wavelength: 5597 To Zero All homed Filter: GGG495 Focus: -8000 Focus: -8000 Shutter: Closed Detector: Idle Detector control Passive Details Details Detector control Details Object: Tricorde To Zero Ready Details Details Object: Tricorde Tost Ready Obs type: IntFlat Integration (s): 1				FCS status:	Passive
To ZeroAll homedNo lampsFilter:156495DetailsDetailsFocus:-8000FCSRotatorDetector:IdlePassiveReadyDetector:IdleDetailsDetailsObject:TestDREMELTricordeAmp mode:SINGLE:BImage: ConstructImage: ConstructObs type:IntFlatImage: ConstructImage: ConstructIntegration (s):1Image: ConstructImage: Construct					
Filter: GGG495 Focus: -8000 Shutter: Closed Detector: Idle Detector: Idle Detector control Details Object: Test Test Ready SINGLE:B Single:B Obs type: IntFlat Integration (s): 1	Vvavelength:	and the second second second	Zero	And the second second second	CONTRACTOR AND A CARDING
Focus: -8000 Shutter: Closed Detector: Idle Detector: Idle Detector control Passive Detector control Details Object: Test Test Ready SINGLE:B Integration (s): 1 Integration (s):	-	and the second	*		and the second se
Shutter: Closed Detector: Idle Detector control Passive Details Details Object: Test Test Ready Amp mode: SINGLE:B Obs type: IntFlat Integration (s): 1	-			Details	Details
Detector: Idle Passive Ready Detector control Details Details Details Object: Test Ready Status Readout mode: Direct Image: Control Image: Control Amp mode: SINGLE:B Image: Control Image: Control Obs type: IntFlat Image: Control Image: Control		100 C		FCC	Detator
Detector control Details Details Object: Test DREMEL Tricorde Readout mode: Direct T Amp mode: SINGLE:B T Obs type: IntFlat T		and the second s			
Detector control Object: Test Test Ready Readout mode: Direct Amp mode: SINGLE:B Obs type: IntFlat Integration (s): 1	Detector	IOLE		and the second s	A COLORADOR
Object: Test Ready Status Readout mode: Direct Image: Single:B Imag	Dete	ector control	6	Details	Details
Object: Test Ready Status Readout mode: Direct Image: Single:B Imag	and the second			DREMEL	Tricorder
Readout mode: Direct Amp mode: SINGLE:B Obs type: IntFlat Integration (s): 1	Object: Test			and the second se	Comparison of the local division of the loca
Obs type: IntFlat	Readout mode:	Direct		Constant of the	Dedicat.
Integration (s):	Amp mode:	SINGLE:B	+		
	Obs type:	IntFlat			
Progress:	Integration (s):	1			
	Progress:				
Status: Idle	Status:	Idle			
Expose Expose	Anna Incide	Expose			

Objectives:

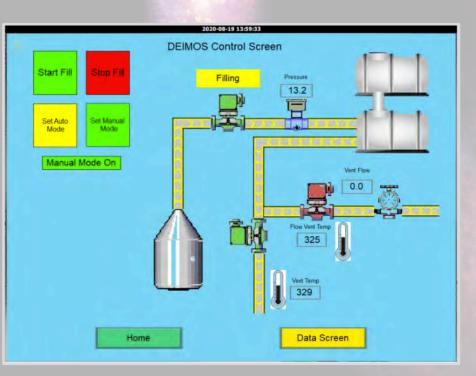
- To replace obsolete host (polo)
- To eliminate dependency of obsolete software **Status:**
- Used for science operations since July 2020
- Pending web docs and update a few scripts used for operations



13

ovember 11, 2020

DEIMOS Autofill Upgrade



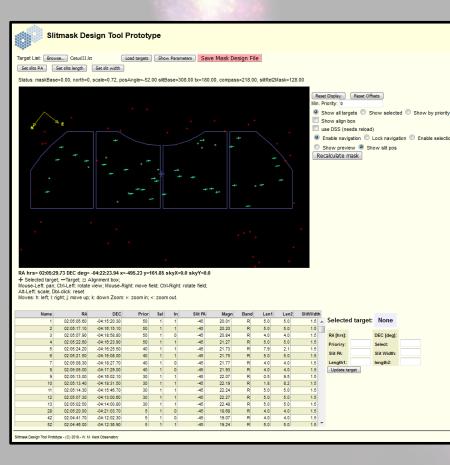
Objectives:

- To eliminate complexity of previous autofill
- To easy access to data, which can be read into keywords
- To simplify operation
- Commonality with KCWI autofill

Status: Completed



Pre-observing software upgrades



Slitmask database migration:

- Main motivation: To eliminate dependency of UCO/Lick (master database on UCO computer).
- Status: Most of the work still pending (Steve Allen focused on KCRM.)

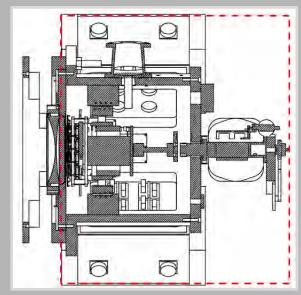
Slitmask design tool replacement:

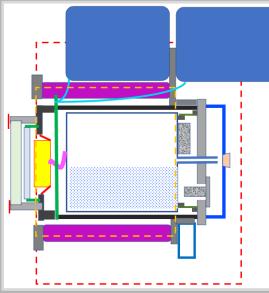
Motivation: To replace dsimulator, which is based on obsolete IRAF code.

• Status:

- Web interface needs debugging.
- Currently testing comparison between masks created with new and old design tool.
- Pending on-sky testing.

DEIMOS throughput upgrade





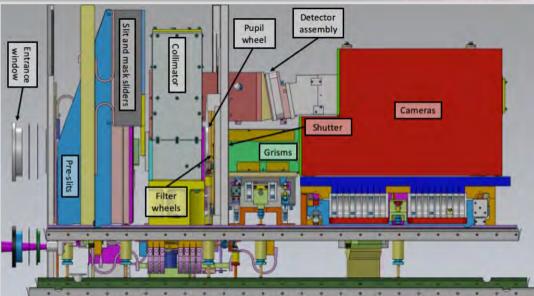
November 11, 2020

- Project led by E. Kirby (CIT).
- Objectives are to upgrade:
 - Science CCD mosaic
 - FCS CCDs
 - Detector dewar
 - Flexure compensation mechanism (hexapod)
- Currently working with the CIT team in preparing NSF MRI proposal for January 2021



NIRC2 (Near-IR Camera 2)







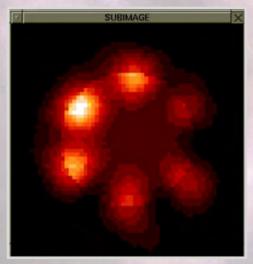
- Institution: Caltech
- PI: Keith Matthews
- First Light: July 29, 2001
- Keck-II AO-fed instrument
- Capabilities: Imaging, coronagraphy and long-slit spectroscopy
- Coverage: 0.9 to 5.5 micron
- Detector: 1024x1024 InSb Aladdin-3
- Pixel scale: 10mas, 20mas, 40mas
- FOV: 10"x10", 20"x20" and 40"x40"
- Spectral resolution: 1200 9700

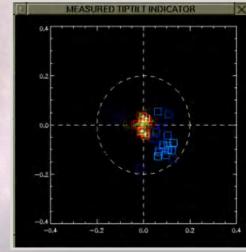
NIRC2 Risk Matrix

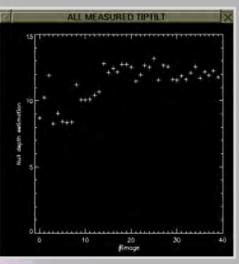
	Very Likely >70% within year					
	Probable >35% within year					
Likelihood of Occurrence	Possible >5% within year				Instrument host	
	Unlikely <5% within year			Other detector electronics	Detector transputers	
	Very unlikely <1% within year					
			Minor: Observation Compromised	Moderate: Observation Interrupted	Serious: Instrument Down one Night	Major: Instrument Down Indefinitely
		Risk Severity, Impact				

Issues

- Detector (alad) server crashes on NIRC2 host (waikoko): Occur almost every night but hardly any time lost. Unknown cause. RPC issue.
- NIRC2 host used to suffer spontaneous reboots. Hardware partially replaced last November. No issues since then.
- Low efficiency of operations with the VVC.

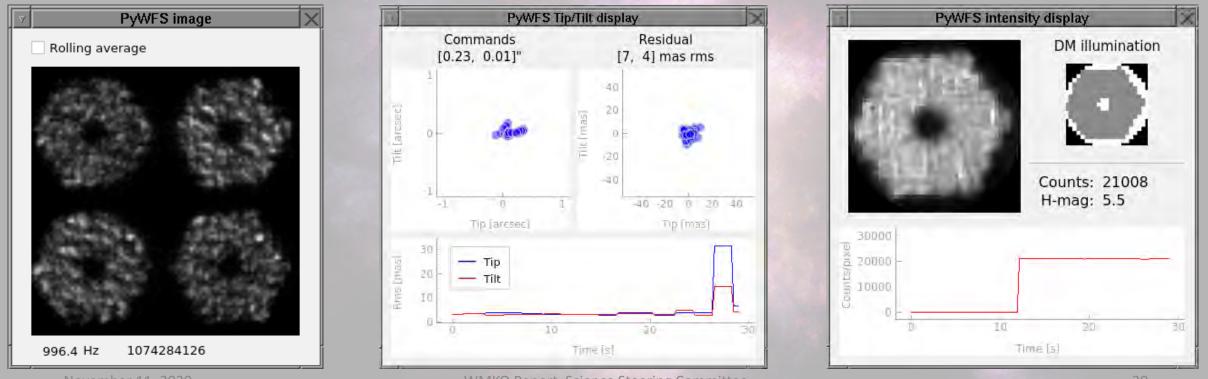






NIRC2 operations improvements

- Updated image writing software:
 - Increased FITS header size to include PyWFS keywords.
 - Fixed long-standing issue with the FITS header END card.
- PyWFS monitoring GUIs available on NIRC2 VNCs.

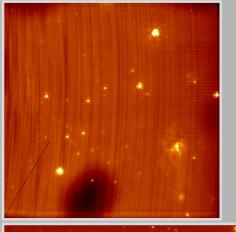


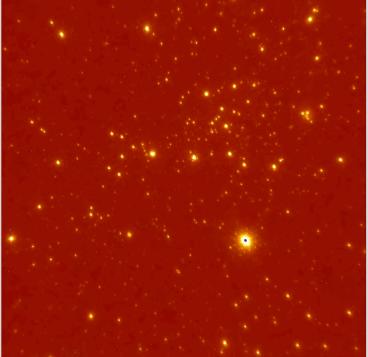
November 11, 2020

WMKO Report, Science Steering Committee

20

NIRC2 vs. OSIRIS imager





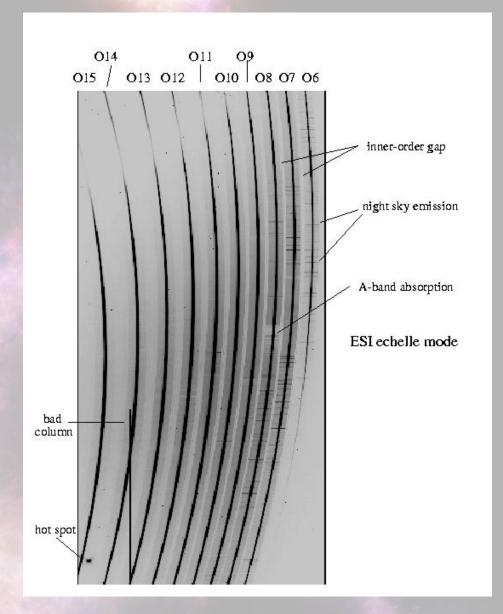
	NIRC2	OSIRIS imager	
Detector	1Kx1K Aladdin-3 InSb	2Kx2K Teledyne H2RG HgCdTe	
Wavelength (µm)	0.9 – 5.3	0.9 – 2.5	
Pixel scale (mas)	10, 20 and 40	10	
FOV (arcsec ²)	10x10, 20x20, 40x40	20x20	
Sub-windowing	Yes	No	
T_exp min (full frame)	0.18s	1.5s	
RON per CDS (e-)	60	23	
Gain (e-/DN)	4	2.2	
1% linearity (DN)	10,000 (40,000 e-)	20,000 (44,000 e-)	
AO Capabilities	PyWFS	TRICK	

November 11, 2020

ESI Jim Lyke



Keck II: Cassegrain 20" slit, Cross-dispersed 3900-11,000 Å, R=13,000



ESI Risk Matrix

	Very Likely						
	>70% within year						
	Probable >35% within year				Cryo Shortage		
Likelihood of Occurrence	Possible >5% within year				Guider Failure	Detector System Failure	
	Unlikely <5% within year					Mechanism or Encoder Failure	
	Very unlikely <1% within year						
		Negligible: Little to no impact on Observation	Minor: Observation Compromised	Moderate: Observation Interrupted	Serious: Instrument Down one Night	Major: Instrument Down Indefinitely	
		Risk Severity, Impact					

ESI Efforts

State Balance

Rotator Incident Report

- On-sky tracking problem investigation led to instrument shake
- Missed lubrication PM during COVID shutdown

• FIX:

- Lubricated rotator bearing
- Removed input biases from rotator amplifiers
- Lowered Amp B error amplifier gain

• Guider failure

- Replaced with spare
- Driving guider replacement project